

ECE153a/253 Embedded Systems

Class Overview

Forrest Brewer

Class Overview

- **What is an Embedded System?**
 - **Physical Constraints: Time, Cost, Power**
 - **Software Engineering in Real Time**
 - **Multiple Stimulus/Response loops**
- **Principles of Structured Design**
 - **Metrics and System Performance**
 - **Correctness and Design Costs**
 - **Specification, Modeling and Abstraction**

Class Logistics

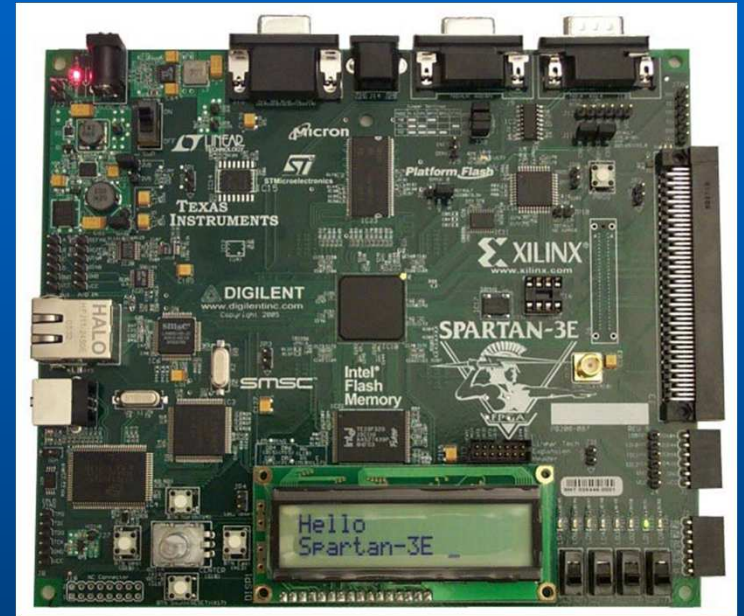
- **2 Weekly Lectures**
 - Papers to read (no textbook --)
 - Ref: “Practical UML StateCharts in C/C++” Miro Samek
 - Weekly Exercises (Homework) 25%
 - Out Wednesday, due Wednesday before 3PM in box
- **Recitation Section 10%**
 - Graded only for undergrads, everyone should go!
- **Final Project + Presentation 25%**
 - Graduates – ‘open’ final project
 - Undergraduates – directed lab
- **4 orchestrated Labs 40%**

Lab Location

- **Linux or Windows can be used**
 - Beware path issues if moving between platforms
 - You can install 14.3 on your own laptop
 - Need to use VPN to access license off campus
- **2-person teams need to obtain:**
 - **Digilent Spartan 3E Starter Board**
 - \$179 from <http://5/www.digilentinc.com/Products/Detail.cfm?NavPath=2,400,792&Prod=S3EBOARD>
 - PMOD SPI Microphone (digilent site)
 - Order asap! – labs start in 1 week
- **ECI Lab (HFH 1st floor)**
 - **Xilinx 14.3 Suite**
 - Licenses served from 2100@license.ece.ucsb.edu

Class Labs

- **Xilinx/Digilent Spartan 3e Card**
 - MicroBlaze/PicoBlaze Processors
 - Verilog/VHDL Programmable Peripheral Devices
 - EDK/SDK tools (ECI)
- **Each 2 person group responsible for own card!**
 - Card: \$179, microphone, < \$200/team



Graduate Section (ECE 253)

- Extra Readings (See Course Bibliography)
- Must Propose final project and have it approved. Final project must use soft platform (i.e. Xilinx or Altera FPGA – DE0-nano \$79 is smaller/faster form factor – beware platform issues!) Groups of 1-2 only.
- Many possible sensors/control PMODS all 5/10 pin SPI
- Beware that SPI is a 'loose' standard, be prepared for at least 2 weeks to verify/validate interface to your hardware in addition to design/coding time. I2C seems more generally stable
- We cannot accept last minute platform changes

Syllabus 1

I. Overview of Embedded Systems

– What is an Embedded System?

- Technology
 - CPU/FPGA/DSP/ASIC
- Hardware and Software
- Real-time, limited resources

– Computation Models and Abstractions

- Why Abstract Models?
- Models: Circuit, RTL, Threads, Tasks
- Modeling Time

Syllabus 2

II. Finite-State Automata

- Overview of Finite Automata
- States (DFA/NFA)
- Sampling and Triggering
- Hierarchy and Concurrency (State Charts)
 - Modality
 - Decomposition
 - C implementation
- NFA Models and Scheduling

III. Process Models

- Kahn Process Models
- SDF

Syllabus 3

IV. Data-Flow and Scheduling

- Loops and Timed Behavior
- Constraints, ASAP, ALAP, Resources
- Exact and Heuristic Scheduling
- Real-Time Task Scheduling
 - Periodic and Priority Policies
 - Rate-Monotone and Deadline Scheduling
 - Priority Inversion
 - Preemption, Overhead and Context
- ILP optimization (IBM CPLEX, LP_SOLVE)

Syllabus 4

V. Real-World:

- **Sensors**
- **Signal Sampling/Noise and Jitter**
 - **Conversion Issues**
- **Motors and Actuators**
 - **DC/Servo, Stepper, Pulse-Drive**
- **Intro to PID Control**

Syllabus 5

VI. Tricks of the Trade

- A. Data Representation
- B. Representation and Computation of Functions
- C. Speculation, Pipelining, Systolic Computation, Trace Optimization
- D. Real-Time Reprise

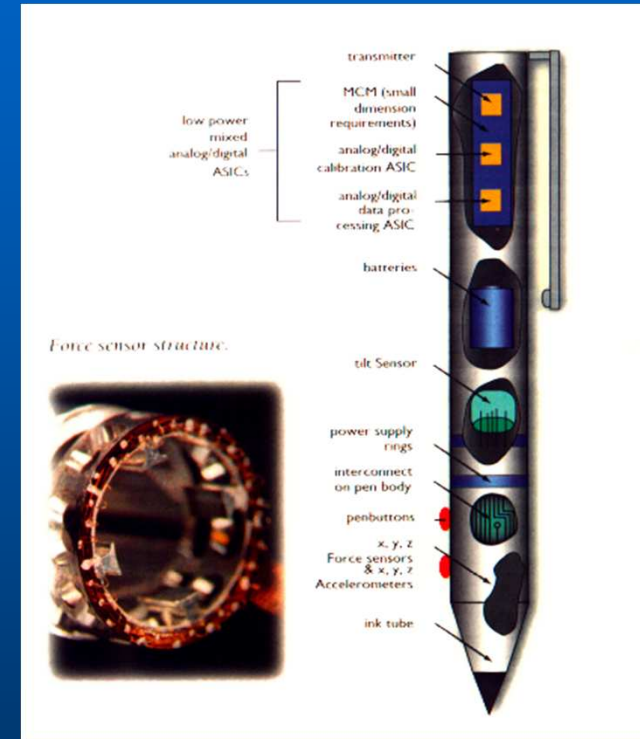
Embedded Systems

- **Computing systems performing specific tasks within a framework of real-world constraints**
 - Automotive: ECS, ABS; Aircraft
 - Network Appliances: Routers, Modems
 - Cell Phones, PDA, Mouse, E-Star Power
 - Printers, Hand Mixers, Toasters, Tires!
- **Microprocessors are Ubiquitous**

Embedded Systems Everywhere!



Tire Pressure Sender



SmartPen

Characteristics of Embedded Systems

- Part of larger system
 - *not* a “computer with keyboard, display, etc.”
- HW & SW application-specific – not G.P.
 - application is known a-priori
 - definition and development concurrent
- Interact (sense, manipulate, communicate) with the external world
- Never terminate (ideally)
- Operation is **time constrained**: latency, throughput
- Other constraints: power, size, weight, heat, reliability
- Increasingly high-performance (DSP) & networked

Why Embed Computers?

- **Enablers**

- New behaviors and applications (GPS, PDA, Wii)

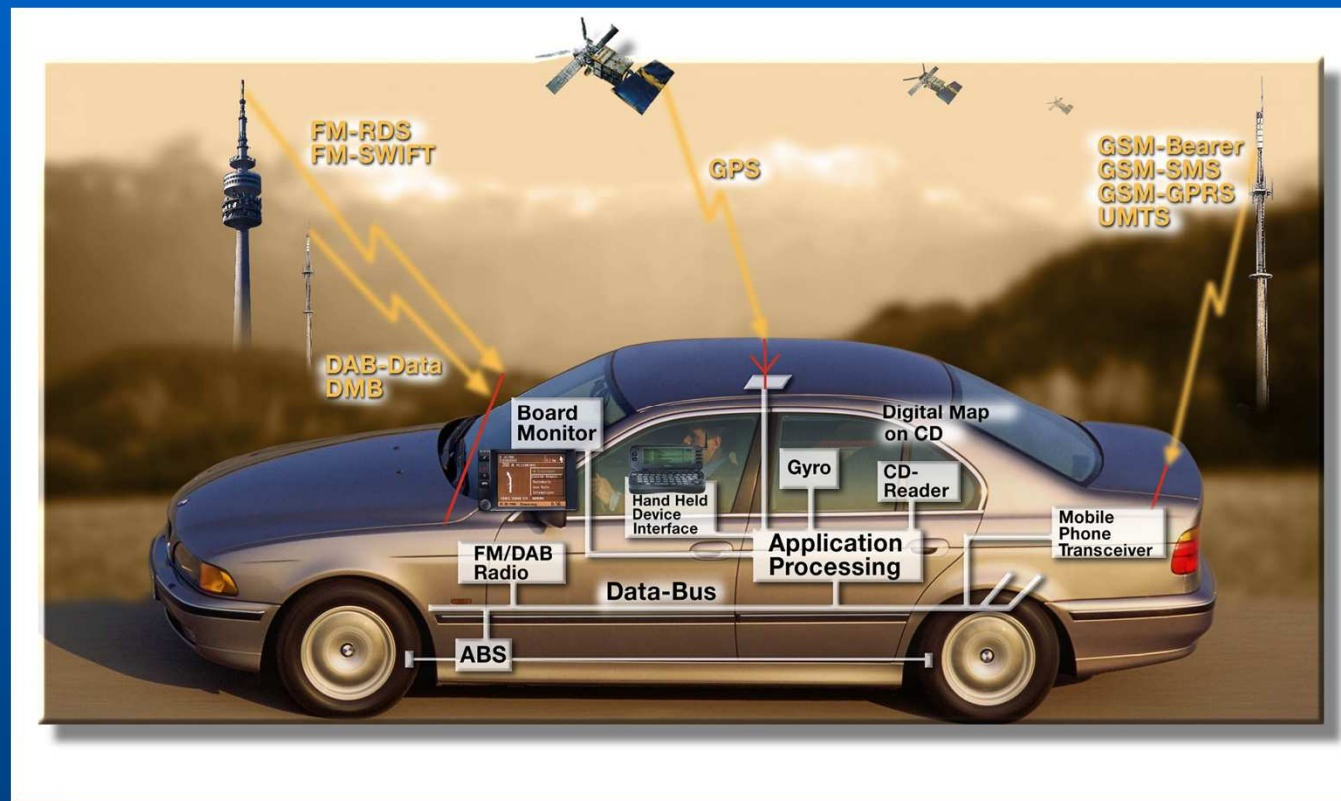
- **Cost!**

- Intelligent Control: workaround manufacturing flaws (Auto ABS), replace antiquated controllers (Toaster), combine functions (Cell Phone)

- **Remote Sensing and Control**

- Expanding Human perception and effectiveness

Embedded Automotive



- More than 30% of the cost of a car is now in Electronics
- 90% of all innovations will be based on electronic systems

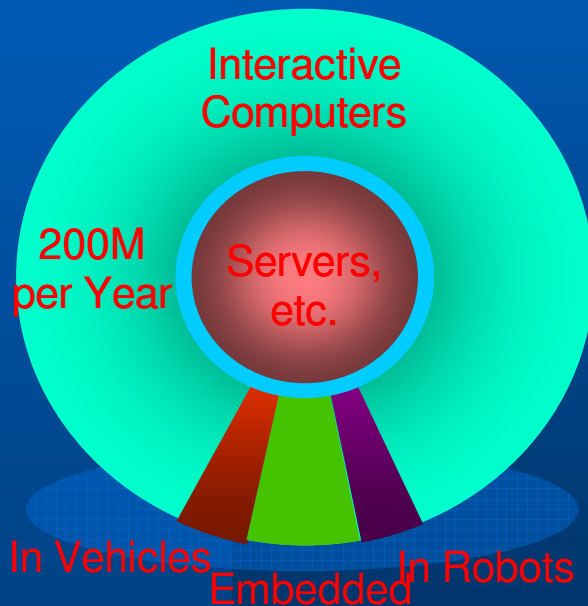
Why do we care? Some Market Tidbits...

- **Specialized devices and appliances replacing PCs**
 - variety of forms: set-top boxes, fixed-screen phones, smart mobile phones, PDAs, NCs, etc.
 - In 1997, 96% of internet access devices sold in the US were PCs, by 2004, shipments far exceeded PCs
 - 2009 Tire Pressure Sensors: 60-70M/yr, Smart cards 100-200M/yr
- **Traditional Products**
 - dependent on computation systems
 - Modern cars: ~100 processors running complex software

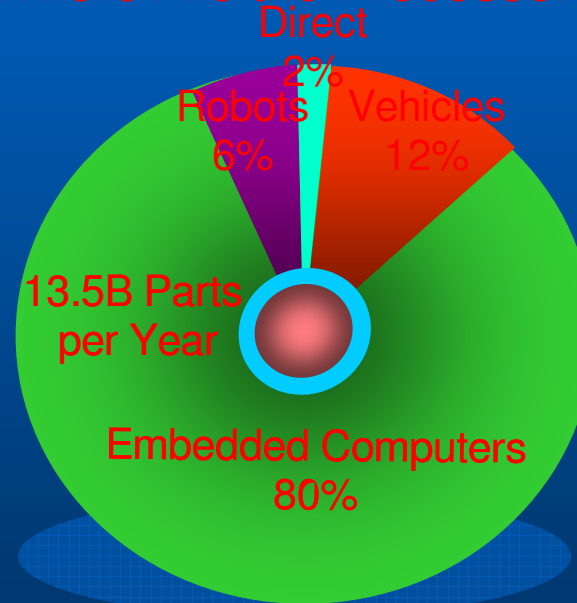
Where are the CPUs?

Estimated 98% of 8 Billion CPUs produced in 2000 used for embedded apps

Where Has CS Focused?



Where Are the Processors?



Look for the CPUs...the Opportunities Will Follow!

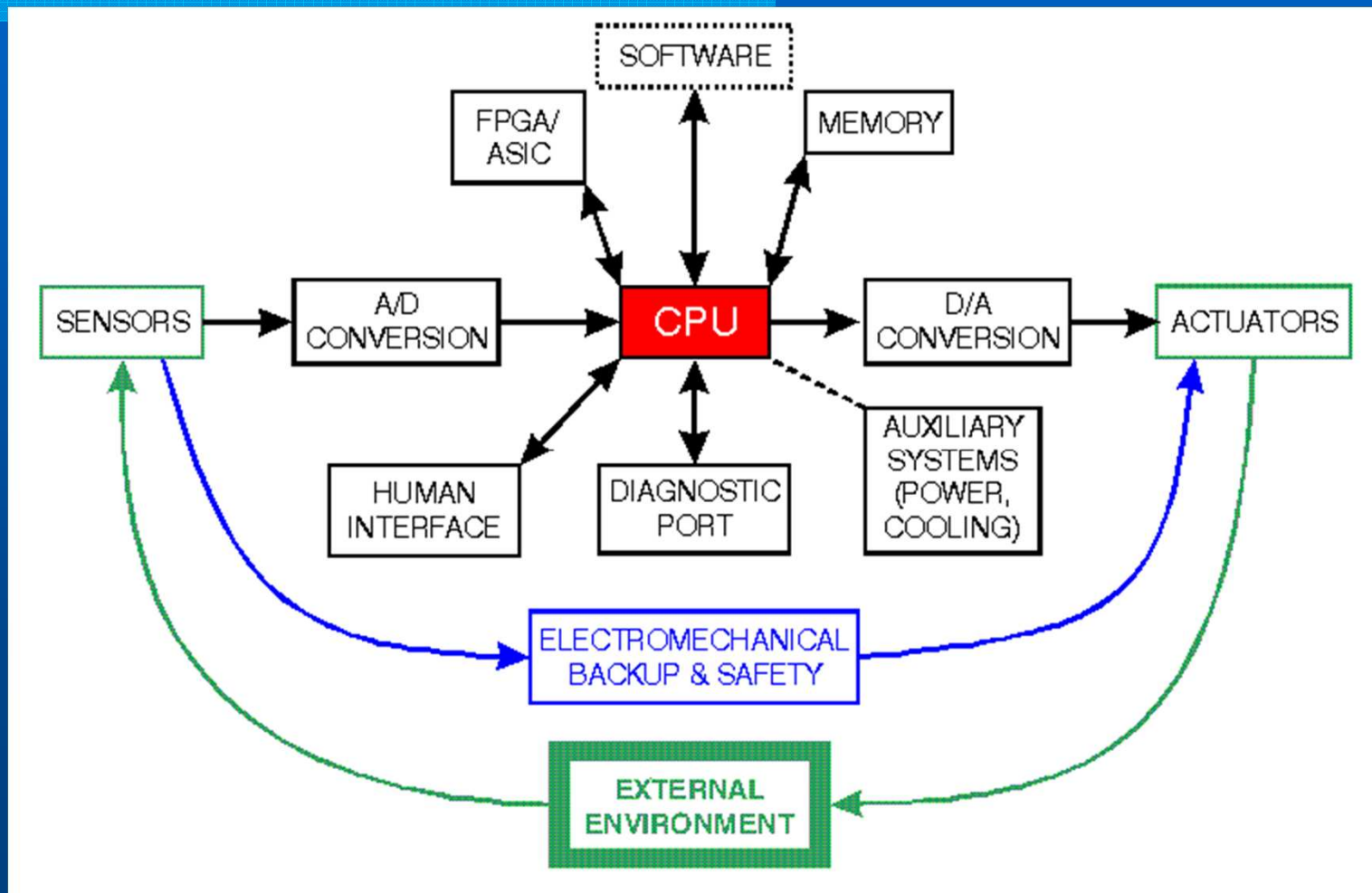
Design Issues

- **Complex Systems!**
 - How to get it working?
 - (on time, on budget)
 - Need for abstraction and design reuse
 - How to test it?
 - Unforeseen Behaviors (Air Bus!)
- **Real Time Physical Embedding**
 - Does it meet constraints?
 - Design Budgeting: Power, Size, Cost, Reliability
 - What are the exploitable design options?

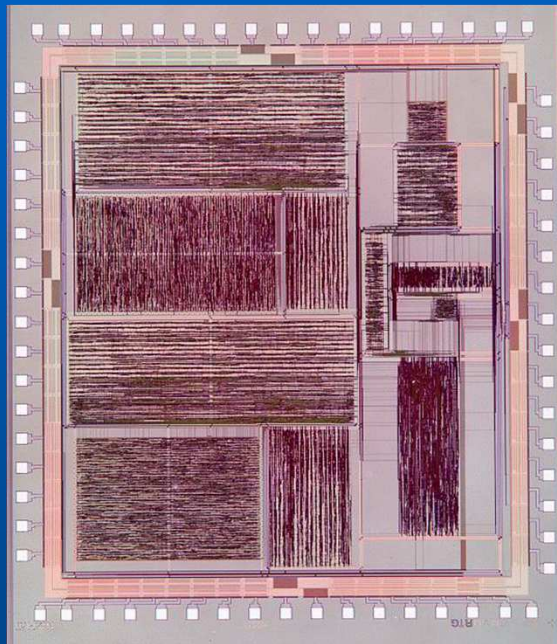
Technology

- **Integrated Processors**
 - Nearly free in production
- **A/D, D/A, Sampling**
 - Interface Analog world to cheap computing
- **MEMS, NEMS, Opto-Devices**
 - Miniature Direct Coupling to Real World
- **Batteries, Solar Cells, Vibration Scavenging, Thermal Gradient Cell**
 - Computation and Communication Power

“Traditional” Software Embedded Systems = CPU + RTOS



ASIC Hardware Embedded System



ASIC Features

Area: 4.6 mm x 5.1 mm

Speed: 20 MHz @ 10 Mcps

Technology: HP 0.5 μ m

**Power: 16 mW - 120 mW
(mode dependent) @ 20
MHz, 3.3 V**

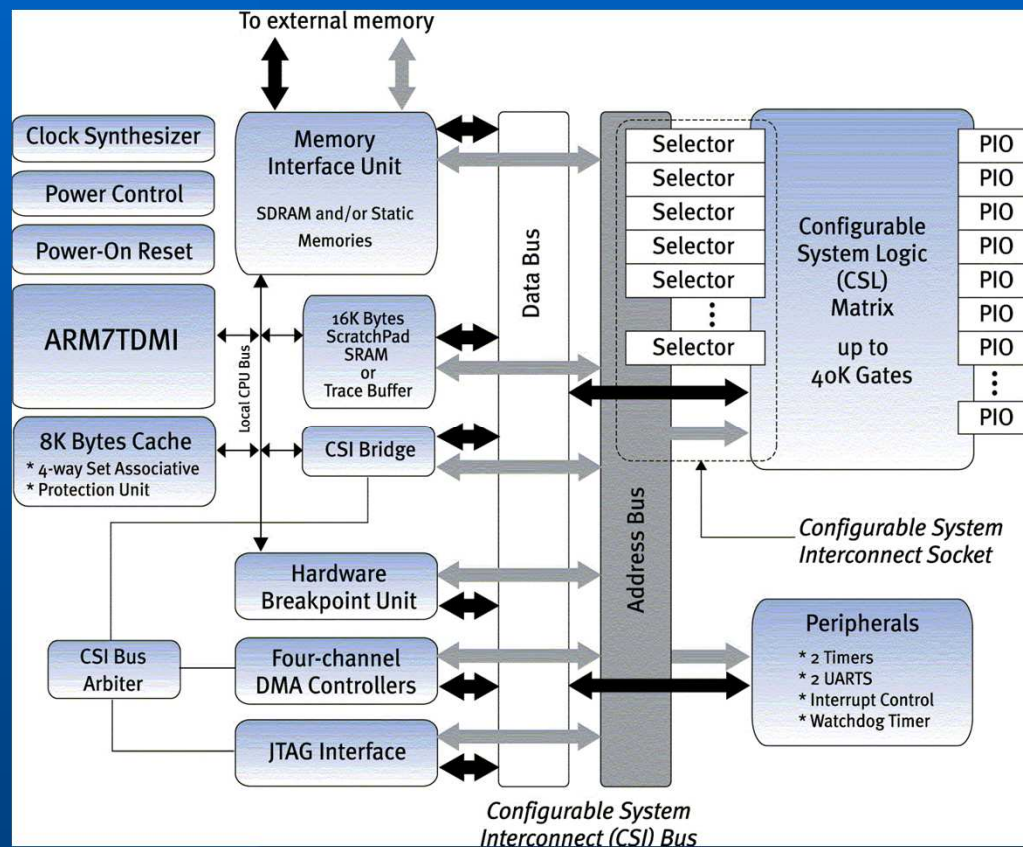
**Avg. Acquisition Time: 10 μ s
to 300 μ s**

- **A direct sequence spread spectrum (DSSS) receiver ASIC**

ASIC Issues

- **Good:**
 - High performance custom peripherals
 - Multiple heterogenous Cores
 - Integrated A/D, D/A, timers ...
 - Low Cost, High performance on-chip communication
 - Low Part Cost in Volume
- **Bad:**
 - Very expensive (\$5-\$75M/design)
 - Very High Risk (Several total failure points)
 - Potentially impossible to Program even if working!

Reconfigurable SoC



Triscend's A7 CSoC

Other Examples

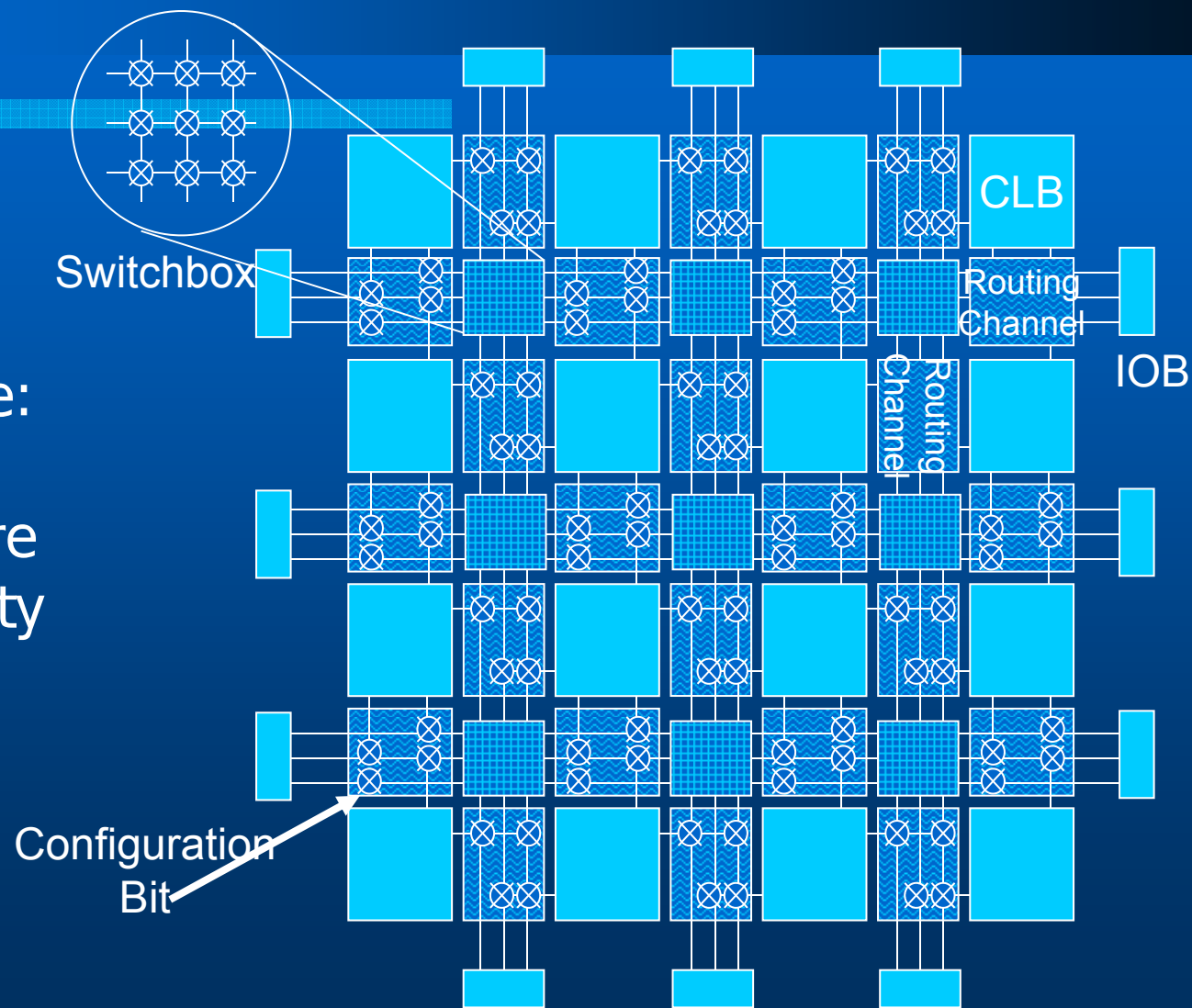
*Atmel's FPSLIC
(AVR + FPGA)*

*Altera's Nios
(configurable
RISC on a PLD)*

*TI's OMAP
(ARM Cortex+
Custom GPU+ TI
DSP)*

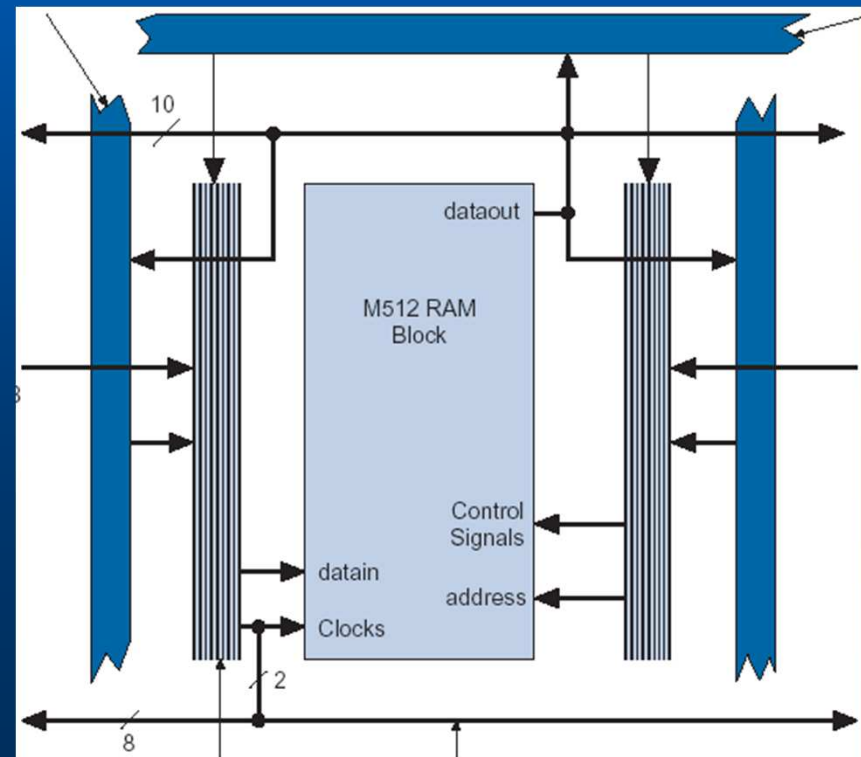
FPGA

FPGA advantage:
performance of
parallel hardware
with the flexibility
of software



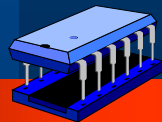
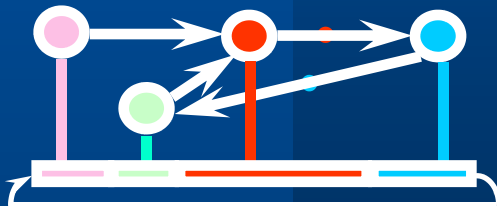
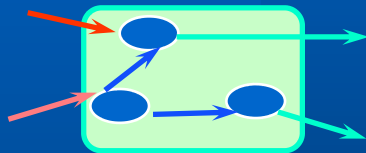
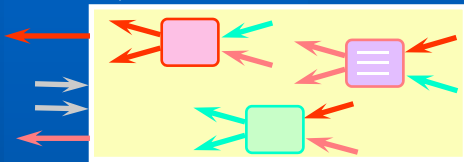
FPGA Embedded RAM

- **Xilinx – Block SelectRAM**
 - 18Kb dual-port RAM arranged in columns
- **Altera – TriMatrix Dual-Port RAM**
 - M512 – 512 x 1
 - M4K – 4096 x 1
 - M-RAM – 64K x 8



Embedded System Design Flow

Environ-
-ment



Modeling

the system, and algorithms involved;

Refining (or “partitioning”)

the function into smaller, interacting pieces

Test Bench Design

Abstractions from the Design, Communication, Storage, and Computation resources

HW-SW partitioning: Allocation

- (1) HW
- (2) SW

Determine power and performance bounds

Scheduling

When are functions executed

Resource Arbitration

Mapping (Implementing)

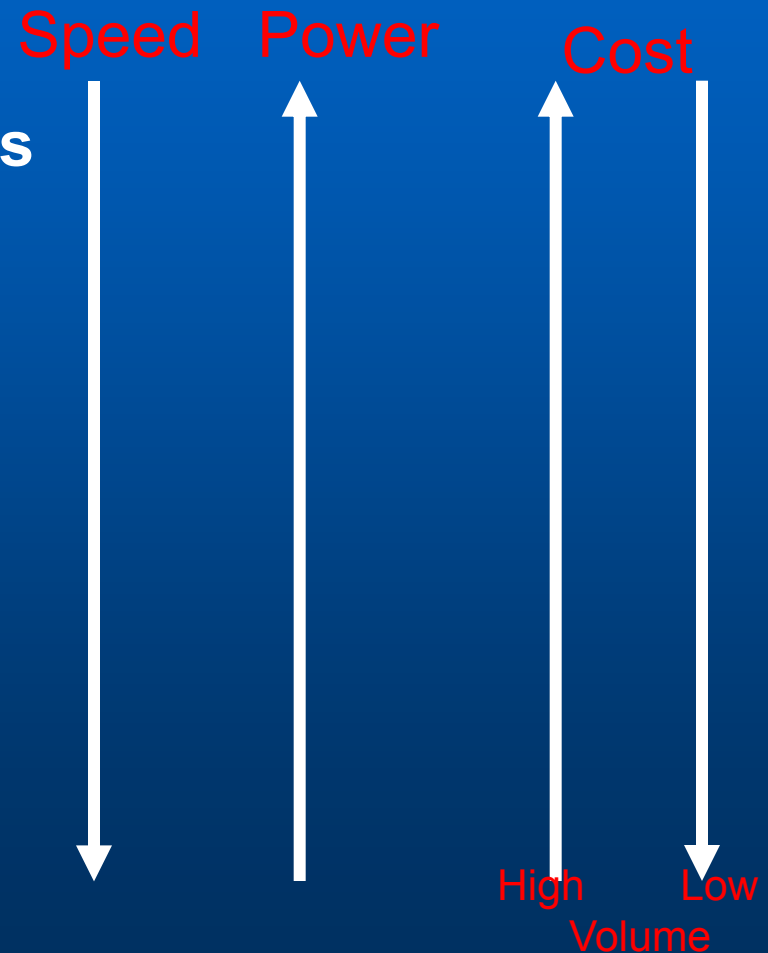
- (1) software, (2) Hardware,
- (3) Coherence/Communication

Testing/Validation

Insitu with Design

Many Implementation Choices

- Microprocessors
- Domain-specific processors
 - DSP
 - Network processors
 - Microcontrollers
- ASIPs
- Reconfigurable SoC
- FPGA
- GateArray
- ASIC
- Full-Custom (COTS)



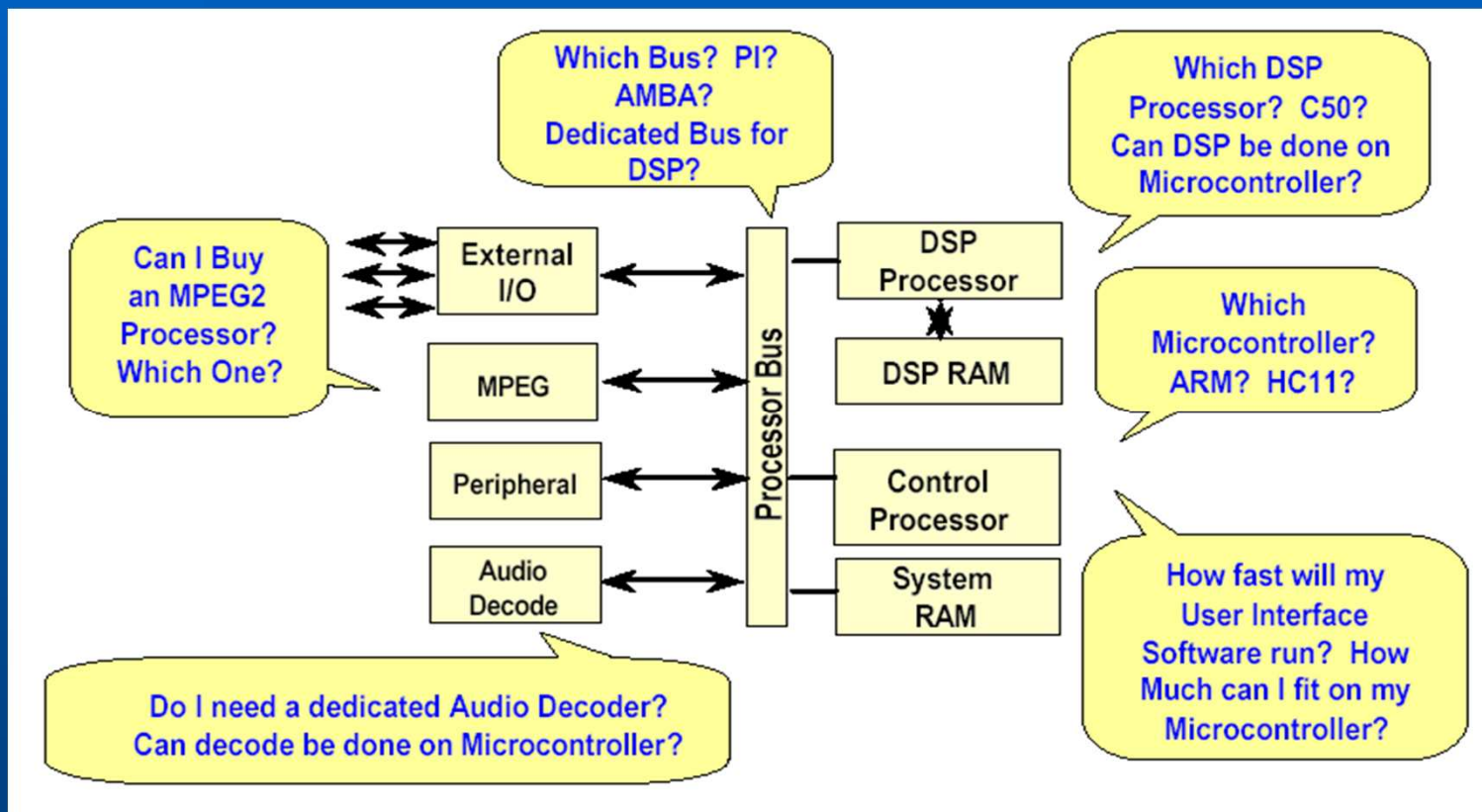
Hardware vs. Software Modules

- **Hardware = functionality implemented in custom architecture**
- **Software = functionality implemented stored program**
- **Key differences:**
 - **Configurability, Adaptability**
 - **Process Time Multiplexing**
 - software modules time multiplexed on a processor
 - hardware modules often mapped to dedicated hardware
 - **Concurrency**
 - processors have serial “thread of control”
 - dedicated hardware has concurrent activity

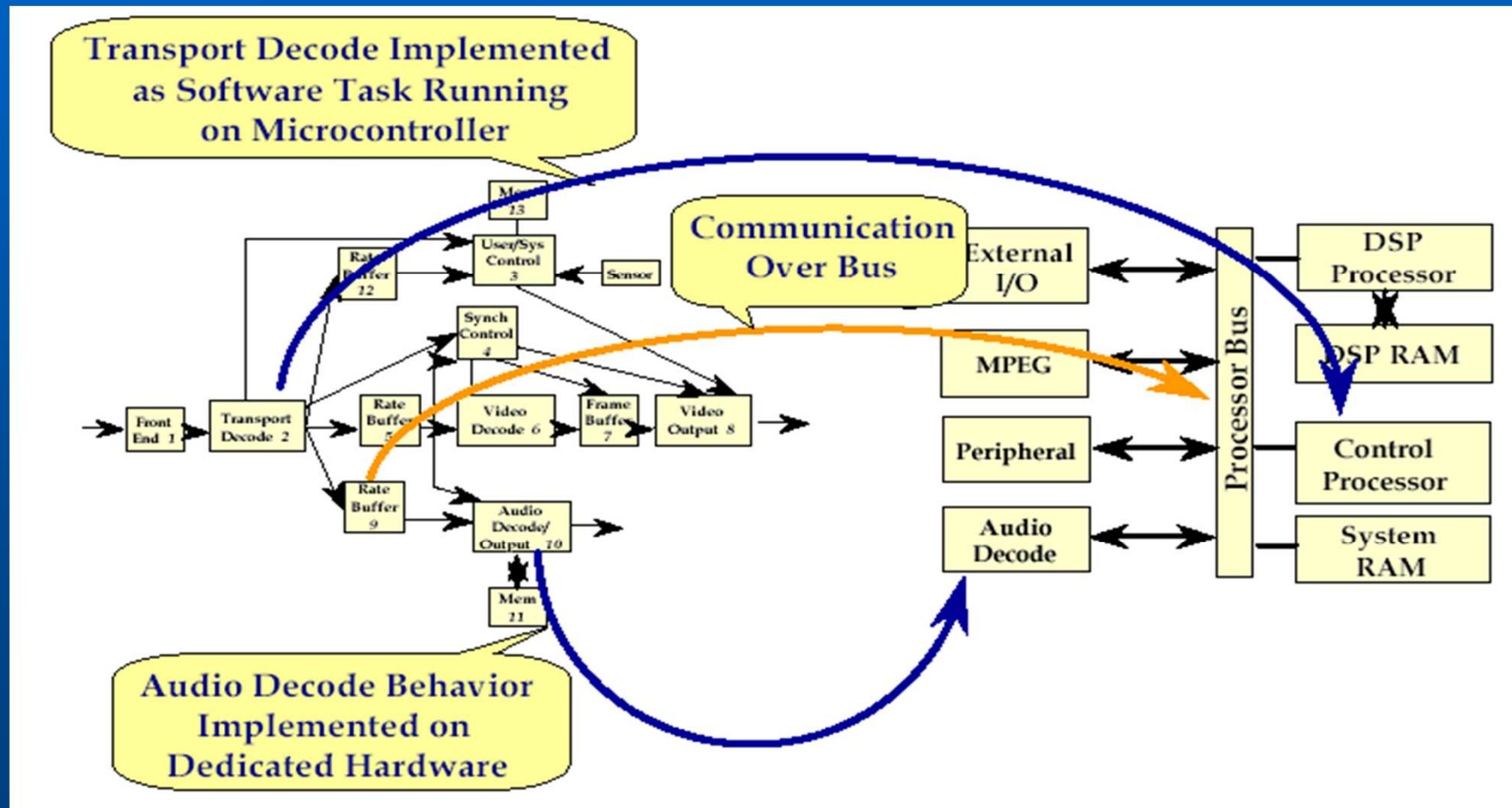
Hardware-Software Architecture

- A significant part of the system design problem is deciding which parts are software, and which are hardware
- Issues:
 - Cost of development
 - System performance
 - Upgrade potential
 - Sales/Implementation Volume
 - Availability of IP
 - Development Time-Line

IP-based Design



Map Behavior to Architecture



Metrics / Models / Abstractions and Systematic Analysis

To make progress, we need objective means to evaluate heterogeneous collections of components, to test and validate correct operation and models to abstract system complexity.

- **Models of Computation**

- Provide metrics on component and system performance
 - Time, Throughput, Power?
- Abstract models as bounds on system behavior
 - Provable or at least Simulation bound on system correctness
- Unfortunately– no complete, encompassing, provable model exists
 - Lots of small provable sub-models: FSM, eFSM, SDL, Kahn Processes
 - Lots of encompassing but undecidable models: RT-FSM, General Modal Logic

- **In search of set of generally useful abstractions**

- Embedded Systems a bit like software compilers in Lisp/Fortran era

This Class

- **Focus on tightly constrained environments and high performance demands**
 - Multi-kHz sample rates
 - Multiple Interrupt sources
 - Relatively small memory, realistic bus environment
- **Will use HFSM approach to organize execution and task dispatch (1-2kbytes)**
- **Labs focus on software side of interface (hardware issues in 153b).**
- **Conceptual understanding of broader aspects of real-time systems.**
 - Scheduling, Priority Inversion, Atomic Code Blocks