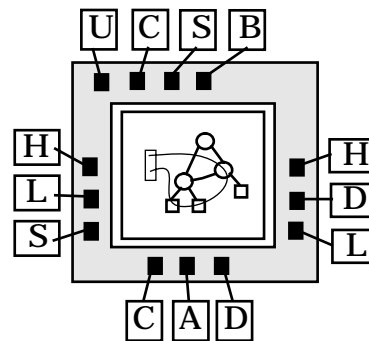


SYNTHESIS from PRODUCTION-BASED SPECIFICATIONS*

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BASIC IDEA

Specification of a Design Using Hierarchy of Productions

Each Production is Sub-Machine

Behavior Due to:

1. Composition of the Sub-Machines

2. HDL Clauses Attached to the Production Grammar

Hardware Analog of Popular Software Techniques

The Production-Based Specification Compiled to VHDL

EXAMPLE

```
port { ...interface information... }

process_front {
    wait until clock'event and clock = '1';
    if      (xc = '1' and xd = '0') then PBS_TOKEN := A;
    elsif  (xc = '1' and xd = '1') then PBS_TOKEN := B;
    elsif  (xc = '0' and xd = '1') then PBS_TOKEN := C;
    elsif  (xc = '0' and xd = '0') then PBS_TOKEN := D;
    end if;
}
```

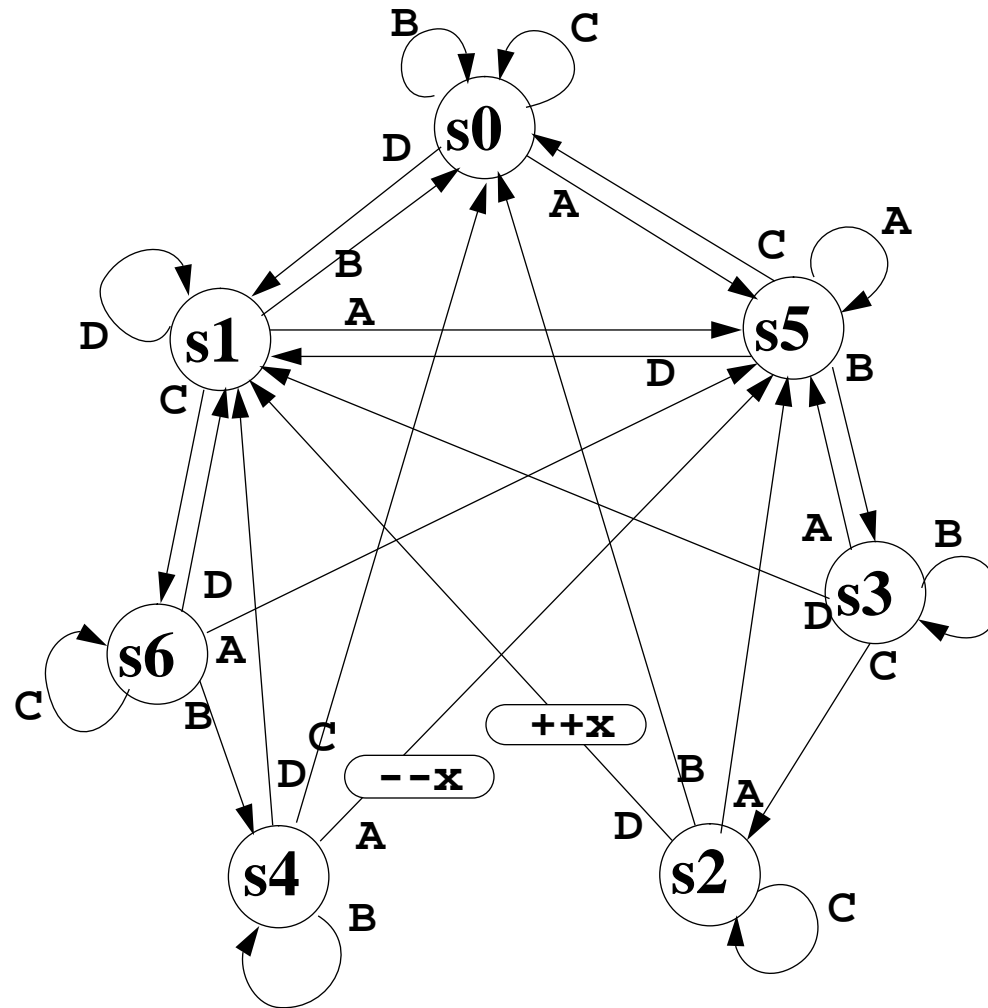
...additional stuff...

::

```
mouse      -> .* event;
event      -> forward | reverse;
forward    -> A B+ C+ D; { x <= x + 1; }
reverse    -> D C+ B+ A; { x <= x - 1; }
```

::

EXAMPLE



Compiled Machine

RELATED WORK

Software Tools: Yacc and Lex

M. A. Jackson

Ullman et. al.

Devadas and Keutzer

METHODOLOGY and ADVANTAGES

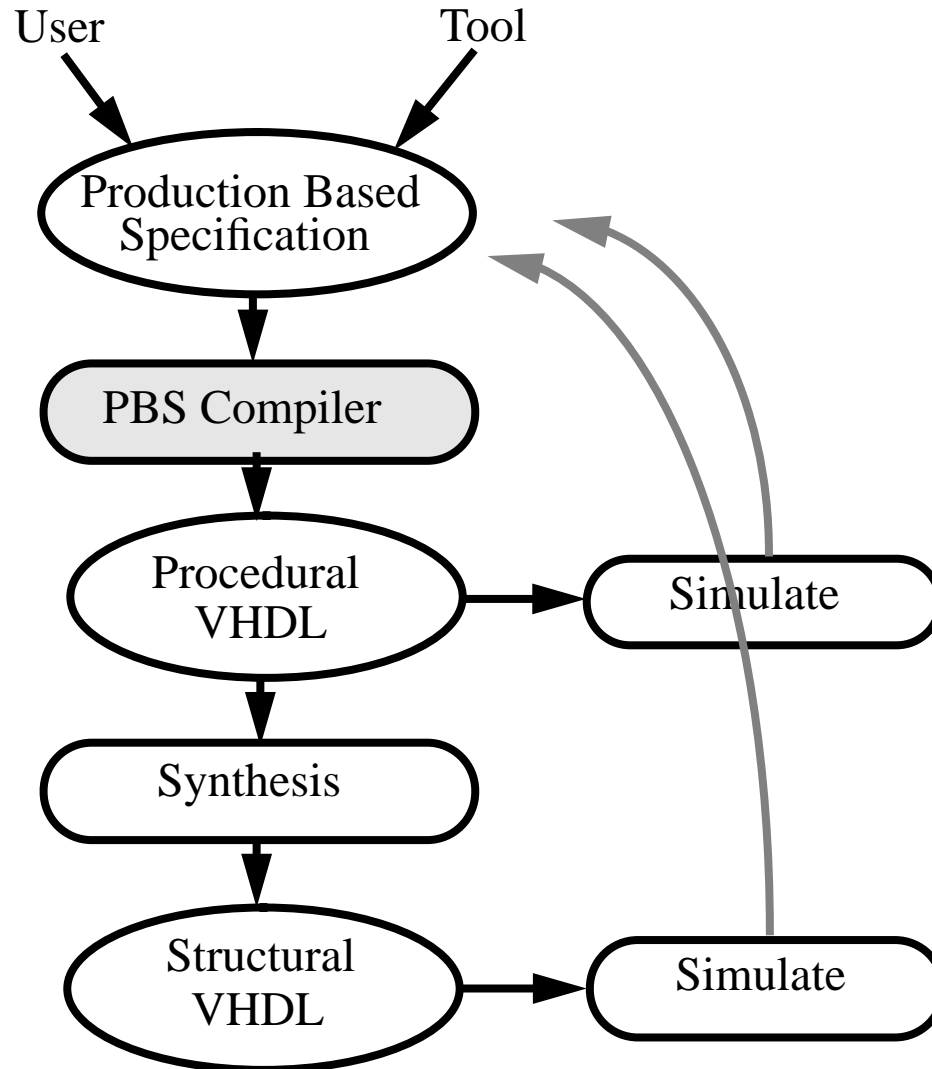
Productions form Natural Partitioning of Design Behavior

Concise Specification of Protocol Engines, Controllers

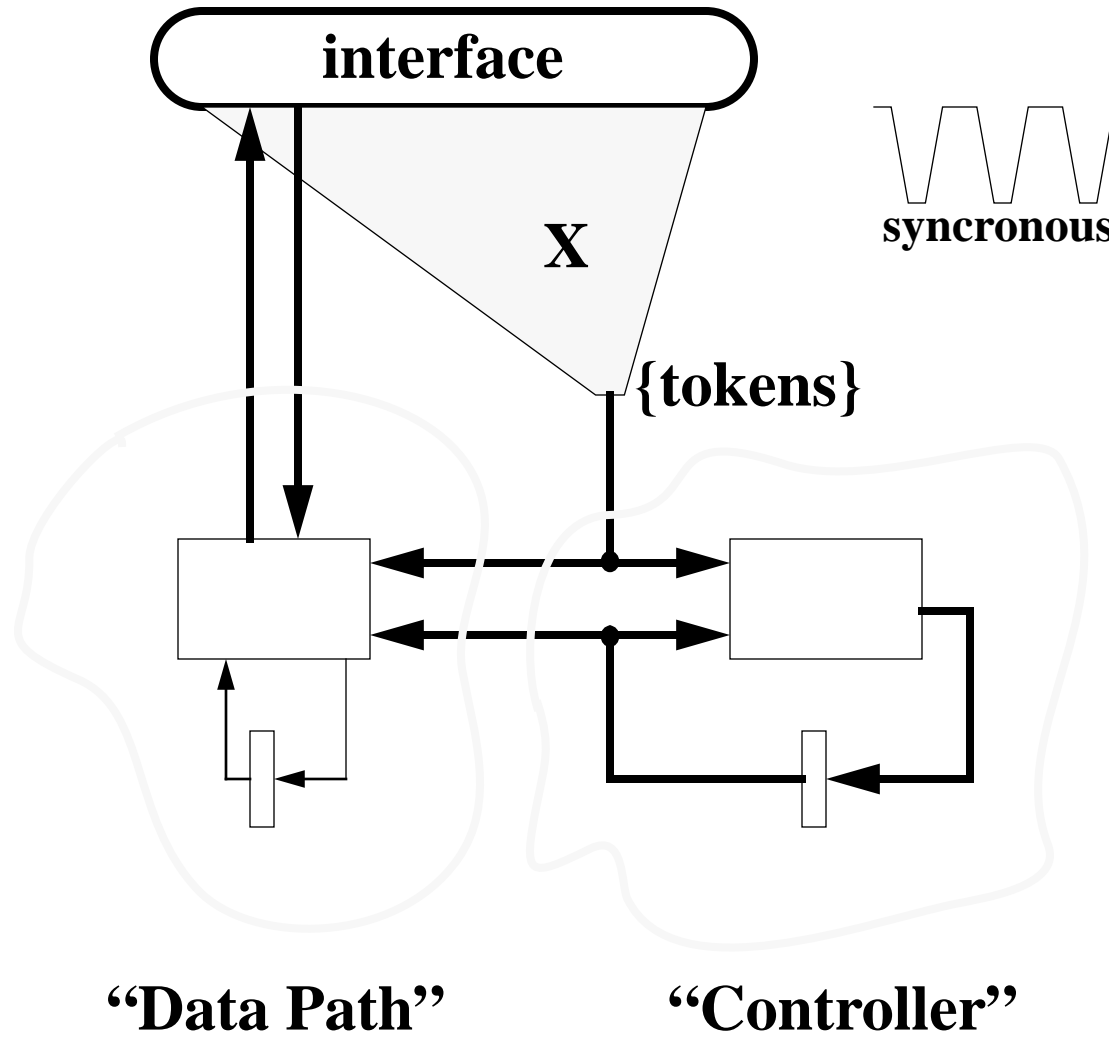
Ensemble Behavior Determined by Additive Facets of Behavior

Descriptive Partitioning of Design

SYSTEM



MODEL



BEHAVIOR MODEL

HDL Actions Viewed by Designer As:

Combinationally Executed in Single Clock Cycle

Executing at the Designated Points in the Protocol

Primitive Actions Conceptually Execute Before Abstract

Ex: `block -> byte^4; { y := 0; }`
 `byte -> bit^8; { y := y + 1; }`

TRANSFORMATIONS!

Any Transformation OK if Behavior Same

HARDWARE vs. SOFTWARE

Timing and Performance Constraints

Lookahead

Specification of Continuous Behavior

Exceptions

EXCEPTION OPERATORS

Ex: $p \rightarrow a!b;$

While in p, if events which can't be described by production a or any other production, then production b active.

Ex: $p \rightarrow a!!;$

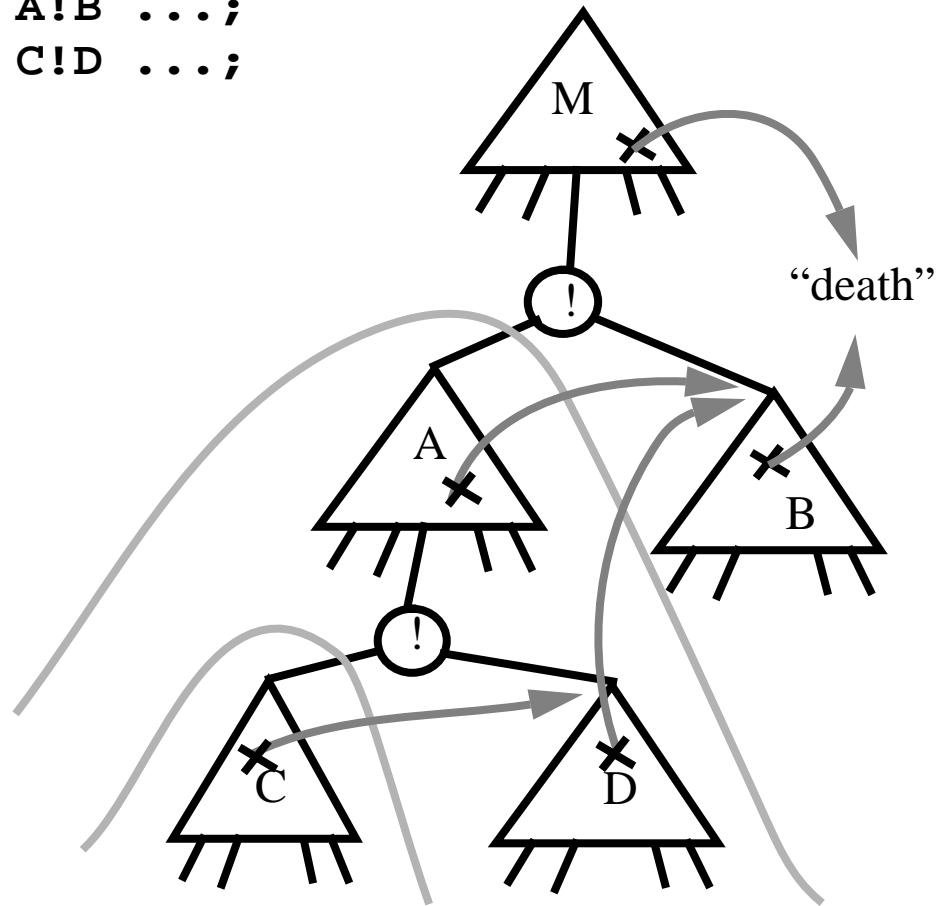
Exception Operators:

Provide Access to Productions' Complement Space

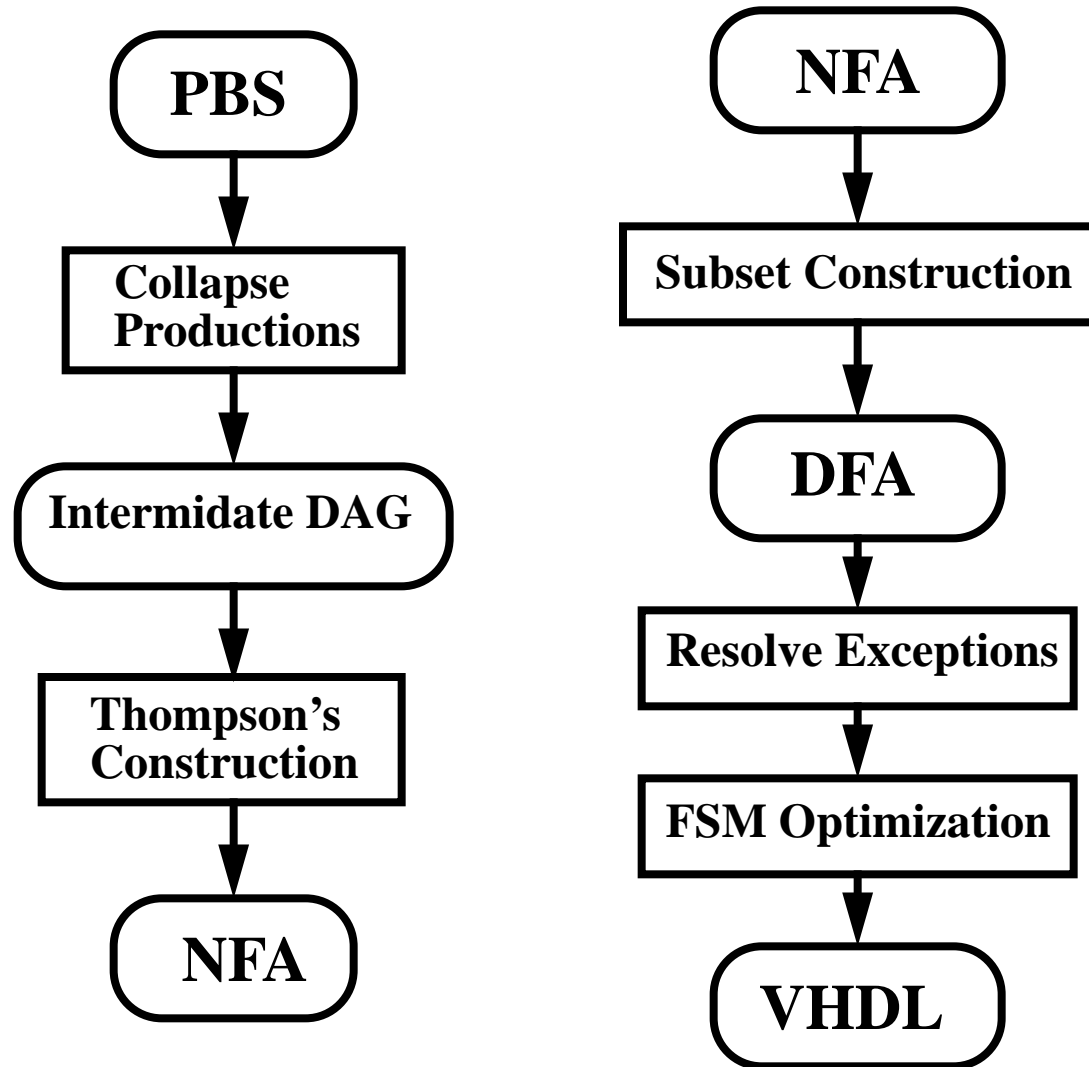
Are Resolved when Deterministic Controller Constructed

EXCEPTION SCOPING

M -> ... **A!B** ... ;
A -> ... **C!D** ... ;



PBS COMPILATION



VHDL SKELETON

```
library work;
use work.<name>_pak.all;
    header{}
entity <name> is
port    port{} );
architecture BEHAVIOR of <name> is
    architecture_decl{}
begin
    PBS_MACHINE: process
        declarations...
        decl{}
    begin
        process_front{}

        machine core...

        process_end{}
    end process;
end BEHAVIOR;
    trailer{}
```

ADD BEHAVIORS...

::

```
mouse -> .* event;  
event -> forward | reverse | pause;
```

```
pause -> A A | B B | C C | D D; {  
    idle_time <= idle_time + 1;  
}
```

```
forward -> A B+ C+ D; {  
    x <= x + 1; idle_time <= 0;  
}
```

```
reverse -> D C+ B+ A; {  
    x <= x - 1; idle_time <= 0;  
}
```

::

SYNTHESIS

(mouse2 / area minimized)

EXPERIMENTS

| metric | mouse1 | mouse2 | cache | parity | bounce | count0 | pager2 |
|-----------------------------------------|---------------|---------------|--------------|---------------|---------------|---------------|---------------|
| No. Productions | 4 | 5 | 5 | 17 | 5 | 5 | 21 |
| No. Actions | 2 | 3 | 2 | 2 | 2 | 3 | 39 |
| lines of productions and actions | 4 | 5 | 11 | 21 | 9 | 4 | 139 |
| PBS size (lines) | 38 | 45 | 41 | 48 | 36 | 41 | 187 |
| procedural VHDL (lines) | 117 | 142 | 83 | 120 | 96 | 108 | 1269 |
| No. NFA states | 25 | 37 | 18 | 1020 | 13 | 30 | 1688 |
| No. DFA states | 7 | 9 | 3 | 16 | 5 | 4 | 536 |
| Transitions with actions | 2 | 10 | 3 | 4 | 2 | 6 | 548 |
| CPU (Sec.) | 0.1* | 0.2* | 0.1* | 2.0* | 0.1* | 0.1* | 18.9* |
| Standard Cells | 62 | 115 | 9 | 44 | 13 | 29 | ** |
| Relative Area | 188 | 313 | 23 | 99 | 42 | 79 | ** |

CONCLUSIONS

**Production-Based Specification and Synthesis
Model and Implementation Presented**

FUTURE WORK

Optimization of Data Flows

High Level Synthesis

Productions of Multiple Token Streams

Current Research

Remove the Abstraction of Interface in the current Token Specification Method

Target Interacting Machines

Utilize the Production Hierarchy in Structuring the Machines